Regression

Linear regression model:

 $\mathbf{y} = \mathbf{X}^T \mathbf{w} + \boldsymbol{\epsilon}, \mathbf{x} \in [0, 1]^{2 \times n},$

Ordinary Least Squares(OLS):

$$\hat{\mathbf{v}} = (\mathbf{X}\mathbf{X}^T)^{-1}\mathbf{X}Y,$$

The most commonly used method: simple, efficient. **Robustness issue**: What if the outliers exists? Only one outlier can destroy the results.



Figure 1:OLS fittings destroyed by the outliers

Research Objectives

Proposing new methods for solving regression problems:

- Robust to outliers.
- Incorporating prior knowledge.

Robust Regression

Model assumption:

$$\mathbf{y} = X^T \mathbf{w}^* + \mathbf{b}^* + \boldsymbol{\epsilon}, \boldsymbol{\epsilon} \sim \mathcal{N}(0, \sigma^2 I_n)$$
(1)

 \mathbf{b}^* : a k-sparse vector; non-zero elements indicate outliers. The robust least-squares regression(RLSR) solves:

$$(\hat{\mathbf{w}}, \hat{S}) = \arg\min_{\substack{\mathbf{w} \in \mathbb{R}^p, S \subset [n] \\ |S| = n-k}} \sum_{i \in S} (y_i - \mathbf{x}_i^T \mathbf{w})^2$$
(2)

Goal: recover the uncorrupted point set S and the regression coefficient \mathbf{w}^* simultaneously. NP hard!

A natural statistical interpretation: maximum likelihood estimation(MLE):

$$(\hat{\mathbf{w}}, \hat{S}) = \arg \max_{\substack{\mathbf{w} \in \mathbb{R}^{p}, S \subset [n] \\ |S| = n-k}} \sum_{i \in S} \log \ell(\mathbf{w} \mid y_{i}, \mathbf{x}_{i}, \sigma^{2})$$

Incorporating Prior information, **Bayesian RLSR**: given prior $p_{\mathbf{w}}(\mathbf{w})$; Posterior:

$$p(\mathbf{y}_S, \mathbf{w} \mid X_S) = p_{\mathbf{w}}(\mathbf{w}) \underset{i \in S}{\Pi} \ell(y_i \mid \mathbf{w}, \mathbf{x}_i, \sigma^2)$$
(3)

Maximizing the log-posterior:

 $(\hat{\mathbf{w}}, \hat{S}) = \arg \max_{\mathbf{w} \in \mathbb{R}^p, |S| = n-k} \log p_{\mathbf{w}}(\mathbf{w}) + \sum_{i \in S} [\log \ell(y_i \mid \mathbf{w}, \mathbf{x}_i, \sigma^2)] \quad (4)$ Two types of attacks are considered:

OAA (oblivious adversarial attack): The outliers are independent to the data.

AAA (adaptive adversarial attack): A more severe attack in which outliers are correlated to data.

Difficulties: Algorithms, Reducing bias caused by prior.

Robust Bayesian Regression via Hard Thresholding

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return $\hat{\mathbf{w}} \leftarrow (XX^T)^{-1}X(\mathbf{y} - \mathbf{b}^t)$

Our Contributions

- We propose new methods that incorporate prior knowledge into robust regression to increase the breakdown point. • We derive the theoretical properties of the proposed algorithms.
- The simulation results show that our methods significantly outperform alternative methods under AAAs. Moreover, BRHT algorithm is also competitive against OAAs.

Theoretical Convergence

Theorem (Convergence of TRIP)

For break point $\|\mathbf{b}^*\|_0 \leq k \cdot n$. Under mild conditions, for k > 1 k^* , it is guaranteed with a probability of at least $1-\delta$ that, for any $\varepsilon, \delta > 0$, $\|\mathbf{b}^{T_0} - \mathbf{b}^*\|_2 \le \varepsilon + O(O(\sigma \sqrt{(k+k^*)\log \frac{n}{\delta(k+k^*)}})) + \varepsilon$ $O(\frac{\sqrt{\Lambda_{k+k}*\lambda_{max}(M)}}{\lambda_{min}(XX^T+M)}) \|\mathbf{w}^* - \mathbf{w}_0\|_2 \text{ after } T_0 = O(\log(\frac{\|\mathbf{b}^*\|_2}{\varepsilon})) \text{ iterations}$ of TRIP.

Theorem (Convergence of BRHT)

For break point $\|\mathbf{b}^*\|_0 \leq k \cdot n$. Under mild conditions, for $k > k^*$, it is guaranteed with a probability of at least $1-\delta$ that, for any $\varepsilon, \delta > 0$, $\|\mathbf{b}^{T_0} - \mathbf{b}^*\|_2 \le \varepsilon + O(\sigma \sqrt{(k+k^*)\log \frac{n}{\delta(k+k^*)}}) + \varepsilon$ $O(\frac{\sqrt{\Lambda_{k+k^*}}\lambda_{max}(M)}{\lambda_{min}(XX^T+M)})\gamma \|\mathbf{w}^* - \mathbf{w}_0\|_2$ after $T_0 = O(\log(\frac{\gamma \|\mathbf{b}^*\|_2}{\varepsilon}))$ iterations of BRHT.

• BRHT is more accurate and behaves significantly better under AAAs, while TRIP stalls during the iterative process.

Figure 3:(a),(b), Convergence diagnostic. (c),(d), Impact of prior $p_{\mathbf{r}}(\mathbf{r})$ and $p_{\mathbf{w}}(\mathbf{w}).$

Reducing Bias :BRHT

Robust **B**ayesian **R**eweighting regression via **H**ard **T**hresholding.

• Prior are typically imprecise.

• To reduce its influence, we introduce a localization parameter \mathbf{r} that reflects the influence of each sample [4]:

 $p(\mathbf{y}, \mathbf{w}, \mathbf{r} | X) \propto p_{\mathbf{w}}(\mathbf{w}) p_{\mathbf{r}}(\mathbf{r}) \prod_{i=1}^{n} \ell(\mathbf{w} | y_i, \mathbf{x}_i, \sigma^2)^{r_i}$

• Intuition: r_i associated with "good" sample (small residuals) tends to be large, i.e., contribute more to posterior density. • BRHT Algorithm:

 $\mathbf{b}^0 \leftarrow \mathbf{0}, t \leftarrow 0,$ while $\|{\bf b}^t - {\bf b}^{t-1}\|_2 > \epsilon$ do $\mathbf{w}^t \leftarrow \mathsf{VBEM}(X, \mathbf{y} - \mathbf{b}^t, p_{\mathbf{r}}(\mathbf{r}), p_{\mathbf{w}}(\mathbf{w}))$ $\mathbf{b}^{t+1} \leftarrow \mathsf{HT}_k(\mathbf{y} - X^T \mathbf{w}^t)$ $t \leftarrow t + 1;$ end while return $\hat{\mathbf{w}} \leftarrow (XX^T)^{-1}X(\mathbf{y} - \mathbf{b}^t)$

VBEM: variational Bayesian expectation maximization. Estimating \mathbf{w} with existence of latent variables.

Simulation Studies

Benchmarks: CRR [1]; Reweighted robust Bayesian regression (RRBR) [4]; Rob-ULA [2].

• TRIP and BRHT are more robust under AAAs.

• BRHT Performs the best in all experiments.









Both algorithms have strong theoretical guarantees that the algorithms **converge linearly** under a mild condition. Future research:

Consistent robust regression. Advances in Neural Information Processing Systems 30 (2017). [2] BHATIA, K., MA, Y.-A., DRAGAN, A. D., BARTLETT, P. L., AND JORDAN, M. I. Bayesian robustness: A nonasymptotic viewpoint. arXiv preprint arXiv:1907.11826 (2019).

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Conceptual Illustration

Figure 4:TRIP and BRHT fittings are perfect!

Conclusion

Two algorithms are proposed for robust regression.

• **TRIP**: By incorporating the prior knowledge, we propose robust regression via hard thresholding. The recovery of coefficients is significantly improved.

• **BRHT**: By employing Bayesian reweighting, reduce the estimation bias caused by prior bias.

• Extend to situations where both \mathbf{y} and X are corrupted. • Further reduces the effect of a prior on the estimation.

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